



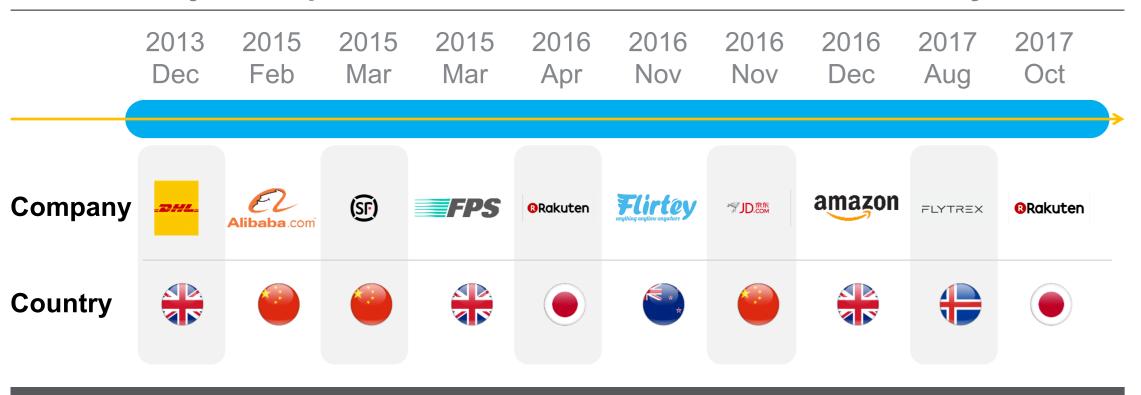
Student: Oriol Rosales Garcia, SCM 2019 **Student**: Antonius Santoso, SCM 2019 Advisor: Dr. Mohammad Moshref Javadi **Sponsor:** MIT Megacity Logistic Lab

Motivation / Background

Drone has emerged as an innovative and viable business solution for commercial last-mile distribution due to lower cost structure (~80% cost reduction), reduced delivery time, farther reach in poor infrastructure areas and less CO2 emission.

Drone delivery is relevant for e-commerce as ~80% of packages delivered by e-commerce weigh less than 5 lbs. Over the past 5 years, major logistic and e-commerce companies have been experimenting with drones as last-mile delivery system

Major companies that tested drone as last mile delivery



Key Question / Hypothesis

Problem statement resembles classic routing problem: "Find the optimal set of routes for a fleet of trucks and drones to serve a set of customers"

Drone routing problem is more complicated than classical Vehicle Routing Problem (VRP) due to **drone-specific constraints**, such as **drone** operational limit (e.g. distance covered, drone endurance, payload) and unique technical characteristics of drone delivery (e.g. one package per trip, no pick-up, no night-time operation).

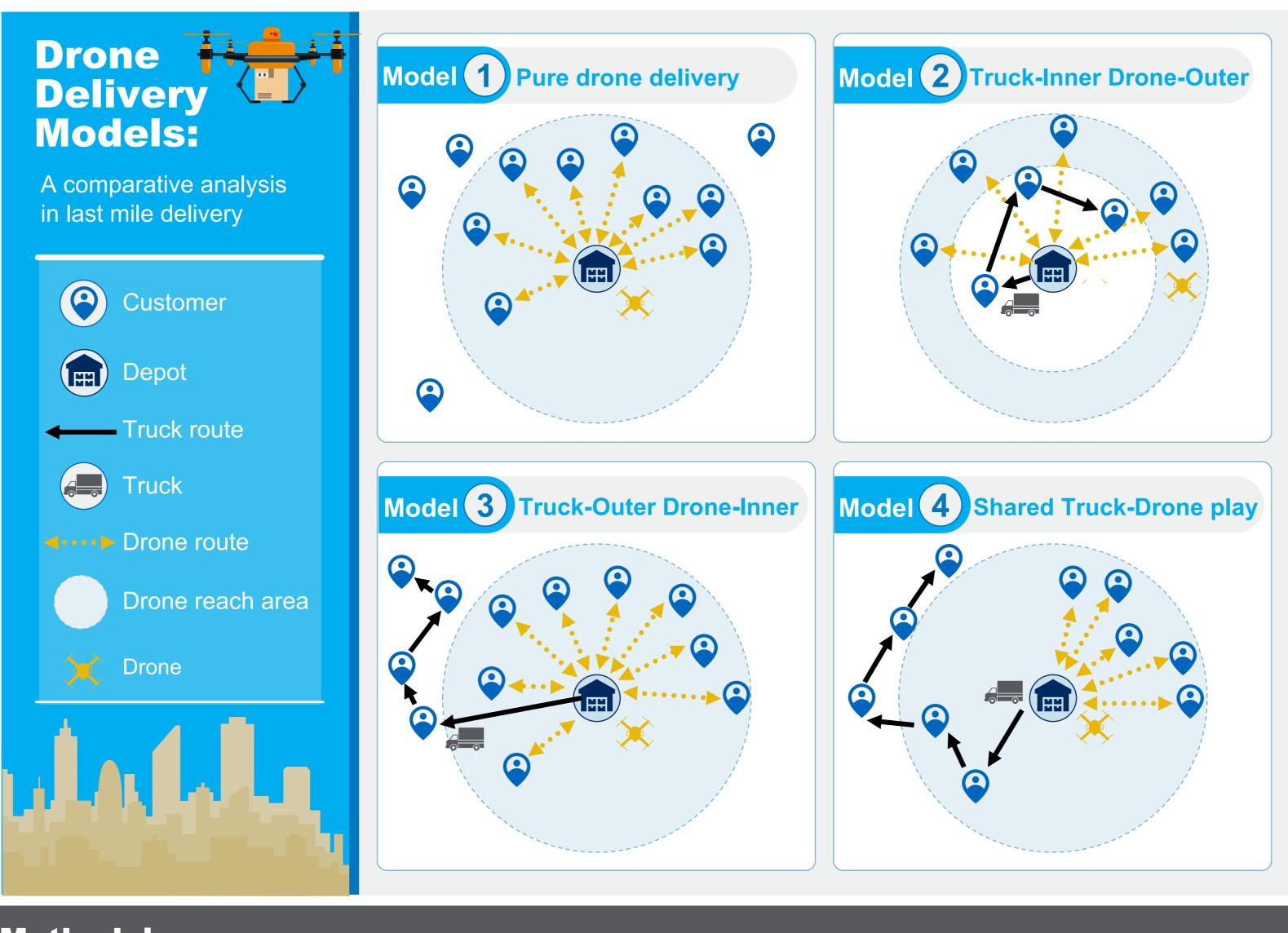
Relevant Literature

Murray C., Chu A. 2015. The flying sidekick traveling salesman problem: Optimization of drone-assisted parcel delivery. Transportation Research Part C 54 (2015) 86-109

Kim S., Moon I. 2018. *Traveling salesman problem with a drone station*. IEEE Transactions on Systems, Man, and Cybernetics: Systems PP (99) (2018) 1-11

Ham A. 2018. Integrated scheduling of m-truck, m-drone and m-depot constrained by time-window, drop-pickup, and m-visit using constraint programming. Transportation research part C 91 (2018) 1-14

Drone Delivery in last-mile distribution



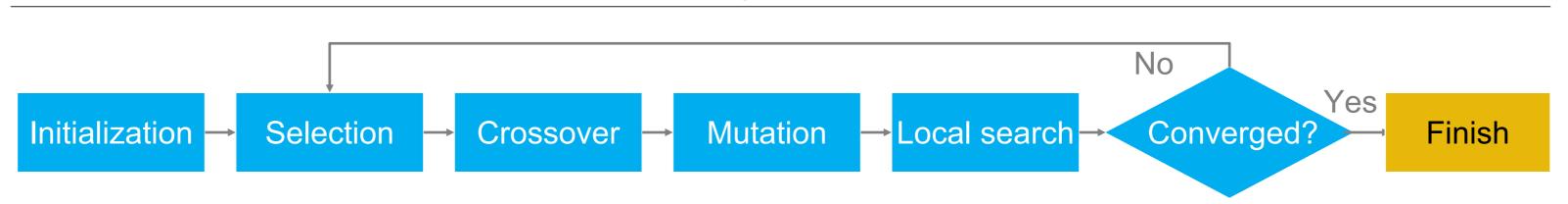
Methodology

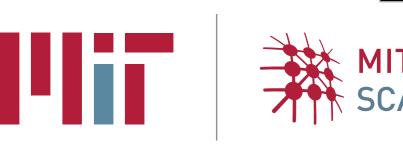
Our project will evaluate the optimal design and operational performance of four different drone delivery models, using real-life last-mile truck delivery data.

A Memetic Algorithm, an extension of Genetic Algorithm, is developed and used to optimize delivery routes of drones and trucks in all the four models.

3 different objective functions (e.g. minimize return time, last customer wait time and total waiting time) and different operating parameters (e.g. drone range, # of drones/trucks) are run to identify the optimum routes.

Memetic Algorithm flowchart

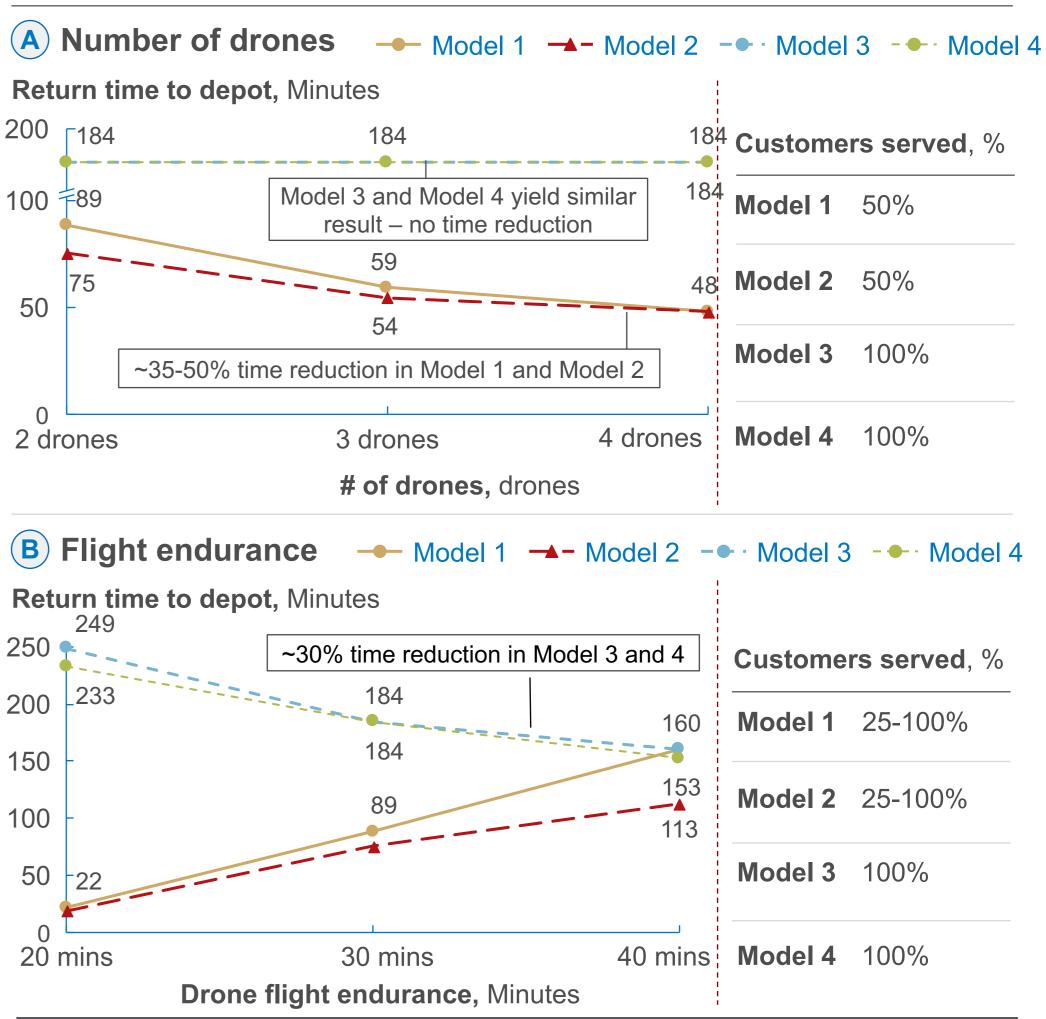




January 2019 Poster Session

Initial Analyses and Results

Initial analyses were run on a reduced dataset to minimize return time to depot, based on different # of drones and flight endurance. Baseline scenario: 2 drones, 1 truck & 30 mins flight endurance. Sensitivity analysis



Expected Contribution

Sensitivity analyses based on Memetic Algorithm for 4 different drone delivery models with different objective functions **Reference framework** for drone application in last-mile delivery.



Oriol Rosales Garcia



BACK TO **KIOSK MENU**

MIT GLOBAL SCALE NETWORK

- ¹⁸⁴ Customers served, %
- **Model 1** 50%
- 48 **Model 2** 50%
- **Model 3** 100%
- 100% Model 4
- **Customers served**, %
- Model 1 25-100%
- Model 2 25-100%
- Model 3 100%
- **Model 4** 100%

Antonius Santoso